

Algebra I

Group Theory

Book 3

A matrix in $GL_2(\mathbb{R})$ is conjugate to $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$ iff it has trace 0 and determinant -1.

If $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \in GL_2(\mathbb{R})$ then A has characteristic polynomial $f(x) = \det(xI - A) = \det\left(\begin{bmatrix} x & 0 \\ 0 & x \end{bmatrix} - \begin{bmatrix} a & b \\ c & d \end{bmatrix}\right)$

$$= \begin{vmatrix} x-a & -b \\ -c & x-d \end{vmatrix} = (x-a)(x-d) - bc = x^2 - \underbrace{(a+d)}_{\text{tr } A} x + \underbrace{(ad-bc)}_{\text{det } A}$$

Cayley-Hamilton Theorem (look it up in any linear algebra book) Some books define the characteristic polynomial of A as $\det(A - xI) = (-1)^n \det(xI - A)$

If $f(x)$ is the characteristic polynomial of an $n \times n$ matrix A , then $f(A) = 0$.

monic:
its leading term is x^n .

In the 2×2 case, $A^2 - (\text{tr } A)A + (\text{det } A)I = 0$ holds as we compute here:

$$A^2 = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a^2+bc & ab+bd \\ ac+cd & bc+d^2 \end{bmatrix}$$

$$A^2 - (\text{tr } A)A + (\text{det } A)I = \begin{bmatrix} a^2+bc & ab+bd \\ ac+cd & bc+d^2 \end{bmatrix} - (a+d) \begin{bmatrix} a & b \\ c & d \end{bmatrix} + (ad-bc) \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a^2+bc - (a+d)a + (ad-bc) & ab+bd - (a+d)b \\ ac+cd - (a+d)c & bc+d^2 - (a+d)d + (ad-bc) \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

If $A \in GL_2(\mathbb{R})$ has trace 0 and determinant -1 then it satisfies $A^2 - 0A - 1I = 0$ so $A^2 = I$

so in the group $GL_2(\mathbb{R})$, A has order ~~1~~ 2. ($\text{tr } I = 2$, not 0)

$f(x) = \det(xI - A)$ may or may not be the smallest degree polynomial that has A as a root. The minimal polynomial of A , $m(x)$, is the monic polynomial of smallest degree satisfying $m(A) = 0$.

Facts (see a linear algebra book):

Roots of $f(x)$ are eigenvalues of A .

$m(x)$ divides $f(x)$ i.e. $f(x) = h(x)m(x)$ for some monic polynomial $h(x)$ (often $h(x) = 1$, $m(x) = f(x)$).

Every eigenvalue of A is a root of $m(x)$.

Theorem Let $A \in GL_2(\mathbb{R})$. Then the following are equivalent:

(i) $\text{tr} A = 0$, $\det A = -1$

(ii) A has order 2 but $A \neq -I$.

(iii) A is conjugate to $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$

We have proved (i) \Rightarrow (iii). And (iii) \Rightarrow (i) is easy. Assume $A = M \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} M^{-1}$ for some $M \in GL_2(\mathbb{R})$.

Then $\text{tr} A = \text{tr} (M \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} M^{-1}) = \text{tr} (M^{-1} M \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}) = \text{tr} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = 0$.

$\text{tr} AB = \text{tr} BA$ if A is $m \times n$, B is $n \times m$ (short proof: see linear algebra. Both equal to $\sum_{i=1}^m \sum_{j=1}^n a_{ij} b_{ji}$)

$\det A = \det M \det \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \underbrace{\det M^{-1}}_{(\det M)^{-1}} = -1$.

$MM^{-1} = I$

$\det(M) \det(M^{-1}) = \det I = 1$

\uparrow
 $\det M$

We must prove (ii) \Rightarrow (iii). If A has order 2 then $A^2 = I$, $A \neq I$. A is a root of $x^2 - 1 = (x+1)(x-1)$ so the minimal poly. of A divides $x^2 - 1$: $m(x) = x^2 - 1$ or $x+1$ or $x-1$ or 1 .

If $m(x) = 1$ then $m(A) = I = 0$. No!

If $m(x) = x-1$ then $m(A) = A-I = 0$ then $A = I$ (No! I has order 1, not order 2)

If $m(x) = x+1$ then $m(A) = A+I = 0$ so $A = -I$ (No! by assumption).

So $m(x) = x^2 - 1$ divides $f(x)$, so $f(x) = x^2 - 1 \Rightarrow \text{tr} A = 0$, $\det A = -1 \Rightarrow$ (i) holds

So ± 1 are eigenvalues of A . Let u, v be eigenvectors corresponding to $1, -1$ i.e. $Au = u$, $Av = -v$.

Let $M = \begin{bmatrix} | & | \\ u & v \\ | & | \end{bmatrix}$ (2×2 matrix having u, v as columns)

$AM = \begin{bmatrix} | & | \\ Au & Av \\ | & | \end{bmatrix} = \begin{bmatrix} | & | \\ u & -v \\ | & | \end{bmatrix} = \begin{bmatrix} | & | \\ u & v \\ | & | \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = M \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \Rightarrow A = M \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} M^{-1}$ i.e. (iii) holds. □

There are two conjugacy classes of elements of order 2 in $G = GL_2(\mathbb{R})$:

- $\{-I = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}\}$ is in a class by itself since $-I \in Z(G)$
- All matrices conjugate to $\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}$ i.e. all matrices with trace 0 and determinant -1.

This includes $\begin{bmatrix} 0 & a \\ 1 & -1 \end{bmatrix}$, $a \in \mathbb{R}$

Consider the dihedral group G of order 8 (the symmetry group of a square) so $|G| = 8$.
 Let's pick generators x, y for G where x is an element of order 4 and y is a reflection (order 2).

$$G = \{1, x, x^2, x^3, y, xy, x^2y, x^3y\}, \quad yx = x^3y \quad \text{i.e.} \quad yxy^{-1} = yxy = x^{-1} = x^3$$

$$\left. \begin{aligned} x^i \cdot x^j &= x^{i+j} \\ x^i \cdot x^j y &= x^{i+j} y \\ x^i y \cdot x^j &= x^{i-j} y \\ x^i y \cdot x^j y &= x^{i-j} \end{aligned} \right\} \begin{array}{l} \text{"If you move } y \text{ past } x^i, \\ \text{it inverts } x^i \rightarrow x^{-i} \text{"} \end{array}$$

$$x^i y x^j y = x^i \underbrace{(yxy)(yx^jy) \cdots (yx^2y)}_{(yxy)^j} = x^i (x^j)^{-1} = x^i x^{-j} = x^{i-j}$$

Presentation for G : $G = \langle \underbrace{x, y}_{\text{generators}} : \underbrace{x^4 = y^2 = 1, yx = x^3y}_{\text{relations}} \rangle$

$$\begin{aligned} x^2 y &= x^2 y \\ y x^2 &= x^{-2} y = x^2 y \end{aligned} \quad \begin{array}{l} i=0, j=2 \\ \text{in the rule} \\ x^i y \cdot x^j = x^{i+j} y \end{array}$$

g	$ g $	$C_G(g)$
1	1	$G, G =8$
x	4	$\langle x \rangle, \langle x \rangle =4$
x^3	4	$\langle x \rangle, \langle x \rangle =4$
x^2	2	$G, G =8$
y	2	$\langle x^2, y \rangle, \langle x^2, y \rangle =4$
$x^2 y$	2	$\langle x^2, y \rangle, \langle x^2, y \rangle =4$
xy	2	$\langle x^2, xy \rangle, \langle x^2, xy \rangle =4$
$x^3 y$	2	$\langle x^2, xy \rangle, \langle x^2, xy \rangle =4$

Centralizer of $g \in G$:

$$C_G(g) = \{x \in G : xg = gx\}$$

$$\mathcal{O}(x) = \{x, x^3\}$$

$$\mathcal{O}(1) = \{1\}$$

$$\mathcal{O}(x^2) = \{x^2\}$$

$$Z(G) = \langle x^2 \rangle = \{1, x^2\}$$

$$C_G(y) = \{1, x^2, y, x^2 y\}$$

is a Klein four-group

$$C_G(xy) = \{1, x^2, xy, x^3 y\}$$

is a Klein four-group

If $\mathcal{O}(g)$ is the conjugacy class of $g \in G$ then $|\mathcal{O}(g)| |C_G(g)| = |G|$.

$$\text{eg. } \begin{array}{l} 1 \times 8 = 8 \\ 2 \times 4 = 8 \end{array}$$

Cosets and Lagrange's Theorem

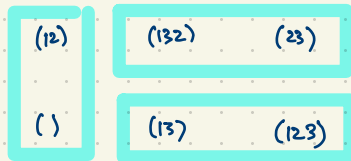
If H is a subgroup of G (multiplicative, at least generically) then a coset of H in G is a subset of the form $gH = \{gh : h \in H\}$. Note: $gH \subseteq G$, not a subgroup in general.

Eg. take $H = \langle (12) \rangle$ in $G = S_3$. List all cosets of H in G . There are exactly three cosets of H in G :

$$\begin{aligned} (1)H &= (1) \{ (1), (12) \} = \{ (1), (12) \} \\ (12)H &= (12) \{ (1), (12) \} = \{ (1), (12) \} \\ (13)H &= (13) \{ (1), (12) \} = \{ (13), (123) \} \\ (23)H &= (23) \{ (1), (12) \} = \{ (23), (132) \} \\ (123)H &= (123) \{ (1), (12) \} = \{ (123), (13) \} \\ (132)H &= (132) \{ (1), (12) \} = \{ (132), (23) \} \end{aligned}$$

$$H, (13)H, (23)H$$

G is partitioned into three cosets, each of size 2.



$$\begin{aligned} |G| &= [G:H] |H| \\ 6 &= 3 \times 2 \end{aligned}$$

(Recall:

A partition of G is a collection of subsets that covers all of G without any overlap.)

Theorem The cosets of a subgroup $H \leq G$ partition the elements of G .

Proof If $g \in G$, then gH is a coset containing g (since $e \in H$). Suppose two cosets aH and bH overlap. i.e. $g \in aH \cap bH$ so $g = ah_1 = bh_2$ for some $h_1, h_2 \in H$, so $aH = gh_1^{-1}H = gH$ and $bH = gh_2^{-1}H = gH$. \square

If $h \in H$ then $h = h_1^{-1}h_1h \in h_1^{-1}H$ so $H \subseteq h_1^{-1}H$.

Conversely, $h_1^{-1}H \subseteq H$

Theorem All cosets of H in G have cardinality $|gH| = |H|$.

Proof A bijection $H \rightarrow gH$ is given by $h \mapsto gh$. An inverse map $gH \rightarrow H$

is given by $x \mapsto g^{-1}x$.

As a corollary, we obtain Lagrange's Theorem: $|G| = \underbrace{(\text{no. of cosets of } H \text{ in } G)}_{\text{the index of } H \text{ in } G \text{ (denoted } [G:H])} \times \underbrace{(\text{size of each coset})}_{|H|}$

i.e. $|G| = [G:H] |H|$

Ex. In S_n , the set of all even permutations is a subgroup A_n . ($n \geq 2$)
The set of all odd permutations is a coset of A_n .

S_n has two cosets of A_n :
(1) $A_n = A_n = \{\text{even permutations}\}$
(2) $A_n = \{\text{odd permutations}\}$

$$|S_n| = n! = \underbrace{[S_n : A_n]}_2 \underbrace{|A_n|}_{\frac{n!}{2}}$$

Ex. In the additive group of \mathbb{R}^3 , a line through the origin is a subgroup.
A coset of this line l is a line parallel to the original line.
The parallel lines to l give a partition of \mathbb{R}^3 .