Linear Algebra

Book 1

Example: Find all (x,y) such that 5x+3y=25 and 2x-7y=-31. 2x - 7y = -3We are asking for the simultaneous solution of a system of two equations in two unknowns of and y 2x - 3y = -31 $2 \times (1) - 5 \times (2) = (3)$ $2 \times 25 - 5 \times (-31) = 50 + 155$ 11 y = 205 Solution: (x,y) = (2,5) is the unique solution. 5x +15 = 25 Example: Find all (r,y) such that 5x+3y=25 and 10x+6y=17. This system is inconsistent: if has no solution. This is inconsistent, 10x+6y=17

Example: Find all (x,y) such that 5x + 3y = 25 and 15x + 9y = 75. This system is consistent but the solution is not curique: there are infinitely many solutions. 5x + 3y = 25 (1) 15x + 9y = 75 (2) 15x+9u=75 A system of m linear equations in n unknowns has the form $\begin{cases}
 a_{11}x_{1} + a_{12}x_{2} + \cdots + a_{m}x_{m} = b, \\
 a_{21}x_{1} + a_{22}x_{2} + \cdots + a_{2n}x_{m} = b,
\end{cases}$ (am X1 + am 2 X2 + ... + am xn = 6m x.,..., x. variables representing unleadures). (aij, b. constats for i f {1, ..., m}, j= {1,2,..., n};

Kim longs a bag of 26 items weighing 226 oz. costing \$34.

Cans of time (\$1 each 502 each) 502 each) x cans of time, y apples, 2 loaves of broad) (6) = (8) - (5) (Kim bought 10 cans of tima, 12 apples, and 4 houses of bread.) The unique solution of this system is (x,y, 2) = (10,12,4) Check! that all three equations are satisfied.

a system of 3 linear equations in

Example with m=n=3:

Matrix formulation of linear systems x + y + z = 26 5x + 8y + 20z = 226 x + y + 3z = 34 $\begin{bmatrix} 1 & 1 & 26 \\ 5 & 8 & 20 \\ 1 & 1 & 3 \\ 34 \end{bmatrix}$ [5 8 20 | 226] ~ [5 8 20 | 226] ~ [5 8 20 | 226] ~ [0 3 15 | 76] ~ [0 1 5 | 32] 5 8 20 | 226] ~ [5 8 20 | 226] ~ [0 3 15 | 76] ~ [0 1 5 | 32] Subtract

Subtract 5 times divide row 2

row 1 from row 2 by 3 Example: Find all (x,y) such that 5x+3y=25 and 2x-7y=-31. $\begin{bmatrix} 5 & 3 & | 25 \\ 2 & -7 & | -3| \end{bmatrix} \sim \begin{bmatrix} 1 & 3/5 & | 5 \\ 2 & -7 & | -3| \end{bmatrix} \sim \begin{bmatrix} 1 & 3/5 & | 5 \\ 2 & -7 & | -3| \end{bmatrix} \sim \begin{bmatrix} 1 & 3/5 & | 5 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & | 2 \\ 0 & 1 & | 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & |$ Solution: (x, y)= (2,5)

Even better : $\begin{bmatrix} 5 & 3 & | 25 \\ 2 & -7 & | -3| \end{bmatrix} \sim \begin{bmatrix} 1 & 17 & 87 \\ 2 & -7 & | -3| \end{bmatrix} \sim \begin{bmatrix} 1 & 17 & 87 \\ 0 & -41 & | -205 \end{bmatrix} \sim \begin{bmatrix} 1 & 17 & 87 \\ 0 & 1 & | 5 \end{bmatrix}$ -31-2×87 subtract 2 times divide row 2 subtract row 2 = -31 - 174 from row 1 = .-205 . Solution: (x,y)= (2,5). Check! 5×2 + 3×5 = 25 Subtract 17 times pour 2 2x2 - 7x5 =-31 from row 1. Elementary four operations:

(i) add a multiple of one row to another

(ii) multiples a row by a nonzero constant

(iii) interchange two rows A ~ B means that A, B are linear systems having the same solutions.

We use Gaussian elimination to reduce A, ~ A, ~ A, ~ ... Am where A, represents the linear system and An represent an equivalent linear system (i.e. having the same solutions) but An is simpler than and An represent an equivalent linear system (i.e. having the same solutions) but An is simpler than A. Each step A: ~ Ait, is obtained by one elementary row operation.

Why just one operation at a time? · ie. y = 5 · · · · · · × migne L'aitely many Soldfign (2,5) Gaussian distribution

[0 0 0], [0 0 4], [0 0 5] are examples of metrices in reduced row echelon form they cannot be simplified any further by clamentary row operations. [0 1 5) is almost reduced; it is in row echelon form For a linear system whose matrix is in row echelon form, we can solve for the unknowns 11, 12, ..., 12 eg. 15 3 7 3 7 is in row echelon form. Every linear system has a unique reduced row achelon form.

In any mon matrix, a pivot is the first nonzero autry in its row.

(Pivots are highlighted above.)

In order for a matrix to be in row echelon form, we must have

In order for a matrix to be in row echelon form, we must have

pivots in any row must occur to the right of pivots in any previous rows;

any zero rows occur at the bottom. Assuming a matrix is already in row echelon form, then to be in reduced now echelon form, we must have every pivot entry must be a 1 . every olumn having a givot has only one noazero entry.

Example: Solve the following linear system of 3 equations in 5 unknowns: $\begin{bmatrix} 1 & 4 & -1 & 2 & 3 & 6 \\ 2 & 8 & -1 & 7 & 4 & 19 \\ -1 & -4 & 4 & 8 & -4 & 26 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & -1 & 2 & 3 & 6 \\ 0 & 0 & 1 & 3 & -2 & 7 \\ -1 & -4 & 4 & 8 & -4 & 26 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & -1 & 2 & 3 & 6 \\ 0 & 0 & 1 & 3 & -2 & 7 \\ 0 & 0 & 3 & 10 & -1 & 32 \end{bmatrix}$ $\begin{cases} x_1 + 4x_2 - x_3 + 2x_4 + 3x_5 = 6 \\ 2x_1 + 8x_2 - x_3 + 7x_4 + 4x_5 = 19 \\ -x_1 - 4x_4 + 4x_3 + 8x_4 - 4x_5 = 26 \end{cases}$ $x_4 + 5x_5 = 11$ $x_5 = t$ is a free parameter. ~ 0 0 0 3 -2 7 This matrix is in row echelon form. This can be used to solve the linear system by back-substitution. X3+3x4-5x5=7 $x_3 = 7 - 3x_4 + 2x_5 = 7 - 3(11 - 5t) + 2t = -26 + 17t$ $x_1 + 4x_2 - x_3 + 2x_4 + 3x_5 = 6$ x2 = s is another free parameter $x_1 = 6-4x_2 + x_3 - 2x_4 - 3x_5 = 6-4s + (-26+17t) - 2(11-5t) - 3t$ Solutions: (x1, x2, x3, x4, x5) = (-42-45+24t, s, -26+17t, 11-5t, t) where s,t are arbitrary. Geometrically, the set of solutions forms a plane (2-dimensional surface) in RS two parameters s,t are coordinates for the plane (303,-9,6,1) The point corresponding to (-42,0,-26,11,0) Solution Set inside RS. $(s, \pm) = (3, 1)$ is (30, 3, -9, 6, 1)is another solution Our system is consistent but the solution is not unique.

0 0 0 0 -24 | -42 | 0 0 0 0 -17 | -26 | 0 0 0 0 5 | 11] $\begin{bmatrix} 1 & 4 & -1 & 2 & 3 & 6 \\ 0 & 0 & 1 & 3 & -2 & 7 \\ 0 & 0 & 0 & 1 & 5 & 11 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & 0 & 0 & -24 & 42 \\ 0 & 0 & 0 & 1 & 3 & -2 & 7 \\ 0 & 0 & 0 & 1 & 5 & 11 \end{bmatrix} \sim \begin{bmatrix} 1 & 4 & 0 & 0 & -24 & 42 \\ 0 & 0 & 0 & 1 & 3 & -2 & 7 \\ 0 & 0 & 0 & 1 & 5 & 11 \end{bmatrix} \sim$ (reduced row echelon. (row echelon form) To solve a linear system in reduced row echelon form, introduce parameters for the free variables (the variables whose columns do not contain a pivot). In the example above, x_2 and x_5 are the free variables. Introduce s,t. $x_2=s$, $x_5=t$ can be chosen freely. Solve for the variables x_1 , x_3 , x_4 using the equations appearing in the reduced row echelor form: $x_3 - 17t = -26$ => $(x_1, x_2, x_3, x_4, x_5) = (-42 - 45 + 24t, s, -26 + 17t, 11 - 5t, t)$ where s,t are (This is the parametric solution in terms of the parameters s,t. The system is consistent, having infinitely many solutions.) As long as the rightmost column has no pivot, the system is consistent. The general solution can be written as

$$(x_{1}, x_{2}, x_{3}, x_{4}, x_{5}) = (-42 - 45 + 24t, s, -26 + 17t, 11 - 5t, t)$$

$$= (-42, 0, -26, 11, 0) + s(-4, 1, 0, 0, 0) + t(24, 0, 17, -5, 1)$$

$$(a_{1}, a_{2}, ..., a_{n}) + (b_{1}, b_{2}, ..., b_{n}) = (a_{1} + b_{1}, a_{2} + b_{2}, ..., a_{n} + b_{n}) \quad (vector addition)$$

$$= (a_{1}, a_{2}, ..., a_{n}) = (cq_{1}, cq_{2}, ..., cq_{n}) \quad (scalar multiplication)$$

$$(a_{1}, a_{2}, ..., a_{n}) = (cq_{1}, cq_{2}, ..., cq_{n}) \quad (scalar multiplication)$$

$$\frac{1}{2} = \frac{1}{3} = \frac{1}$$

Algebraic operations for matrices

If $A = \begin{bmatrix} 2 & 3 \\ 1 & -1 \end{bmatrix}$ then $A^2 = \begin{bmatrix} 2 & 3 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 7 & 3 \\ 1 & 7 \end{bmatrix}$, $A^3 = A^2A = \begin{bmatrix} 7 & 3 \\ 1 & 4 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 17 & 18 \\ 6 & -1 \end{bmatrix}$

Recall: the linear system
$$5x+3y=25$$
 has a unique solution $(x,y)=(2,5)$.

One was to solve this: $2x+y=-31$ has a unique solution $(x,y)=(2,5)$.

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Matrix (i.e. orline vector of length 2) and $b=[33]$ is a $2x+1$ matrix of constant.

Here $A=\begin{bmatrix} 5 & 3 \\ 2 & -7 \end{bmatrix}$ $\begin{bmatrix} x \end{bmatrix}=\begin{bmatrix} 25 \\ -3 \end{bmatrix}$ i.e. $\begin{bmatrix} 5x+3y \\ 2x-7y \end{bmatrix}=\begin{bmatrix} 25 \\ -51 \end{bmatrix}$

$$Av=b$$
 says $\begin{bmatrix} 5 & 3 \\ 2 & -7 \end{bmatrix}\begin{bmatrix} x \end{bmatrix}=\begin{bmatrix} 25 \\ -3 \end{bmatrix}$ i.e. $\begin{bmatrix} 5x+3y \\ 2x-7y \end{bmatrix}=\begin{bmatrix} -51 \\ -51 \end{bmatrix}$

Compare: To solve $Ay=b$, multiply both sides on the both by $A=\frac{1}{41}\begin{bmatrix} 7 & 3 \\ 2 & -5 \end{bmatrix}=\begin{bmatrix} \frac{1}{41} & \frac{41}{41} \\ 41 & 2 & -5 \end{bmatrix}$

$$Av=b$$

$$A^{2}=b$$

$$A^{2}=b$$

$$A^{3}=b$$

$$A^{2}=b$$

$$A^{3}=b$$

$$A$$

We say A and B commute if AB = BA.
Which 2x2 motrices commute with A= [34]? Answer by solving the appropriate linear system of a conditions in 9 menous set B = [x y]. In order or AB = BA we require $\begin{bmatrix} x+2 & 3y+\omega \\ 4z & 4\omega \end{bmatrix} = \begin{bmatrix} 3 & 1 \end{bmatrix} \begin{bmatrix} x & y \\ z & \omega \end{bmatrix} = \begin{bmatrix} x & y \\ z & \omega \end{bmatrix} \begin{bmatrix} 3 & 1 \\ 3z & z+4\omega \end{bmatrix}$ 8, 2 are basic variables (in the pivot columns) y, w are free variables (non-pivot columns) Introduce st as parameters. y=s, w=tTutroduce st as parameters. y=s, w=tand solve for x,2: x=-s+t, z=0 so $B=\begin{bmatrix} s+t & s \\ 0 & t \end{bmatrix}=s\begin{bmatrix} 0 & 0 \\ 0 & t \end{bmatrix}=s\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}+t\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$, $\begin{bmatrix} 0 & 0 \\ 0$ Check: If s=1, t=0 then B= [0 0] and BA = AB. [0 0][3 1] = [3 3] [0 0] $\begin{bmatrix} 3 & 1 \\ 0 & 4 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} -3 & 3 \\ 0 & 0 \end{bmatrix}$ Reprosentation of linear systems in matrix form. Ax=6
Restricular and general solutions
Null vectors
Homogeneous linear systems Ax=0 for Friday's Quiz:

Nul (A) = {x \in R : Ax = 0 \in R^m} is the null space of A. It's vectors are called null vectors.

Every linear system has the form Ax = b (for m linear equations in my AxI mxI n unknowns). $\begin{cases} x_1 + 4x_2 - x_3 + 2x_4 + 3x_5 = 6 \\ 2x_1 + 8x_2 - x_3 + 7x_4 + 4x_5 = 19 \\ -x_1 - 4x_4 + 4x_3 + 8x_4 - 4x_5 = 26 \end{cases}$ $A = \begin{bmatrix} 1 & 4 & -1 & 2 & 3 \\ 0 & 0 & 1 & 3 & 2 \\ 0 & 0 & 0 & (3 & 5) \end{bmatrix}, \quad X = \begin{bmatrix} 7 & 1 \\ 7 & 2 \\ 7 & 3 \\ 7 & 4 \end{bmatrix}$ $\begin{bmatrix} 1 & 4 & -1 & 2 & 3 \\ 0 & 0 & 1 & 3 & -2 \\ 0 & 0 & 0 & 1 & 5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{bmatrix} = \begin{bmatrix} 6 \\ 7 \\ 11 \\ 3 \times 1 \end{bmatrix}$ Some prefer to write & or x instead of x. or even & (bold face) or x. for us, context is used to determine whother we are talking about a matrix, a vector, a scalar, a set, a linear transformation, a 3×5 5×1 Some linear systems are incosistent (meaning that they vector space of c.

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have no solutions). If a linear system Ax=b is consistent than its

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Salations have the form $x=a+c_1v_1+c_2v_2+\cdots+c_kv_k$ for some particular solution x=a; c_1,\ldots,c_k (constants) and v_1, \dots, v_k are independent solutions of Ax = 0.

The solutions of the example Ax = b above have the form $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -42 \\ 0 \\ -26 \\ 17 \end{bmatrix} + 5 \begin{bmatrix} 0 \\ 0 \\ 17 \\ 1 \end{bmatrix} = \begin{bmatrix} -42 \\ -46 + 24t \\ 0 \\ 17 \end{bmatrix} = \begin{bmatrix} -42 \\ -26 \\ 175 \\ 1 \end{bmatrix} = \begin{bmatrix} -42 \\ 175 \\ 1 \end{bmatrix} = \begin{bmatrix}$ Vid 7 Solution Set Cie. A V2 Solutions Solutions The gentral

 $A = \begin{bmatrix} 1 & 4 & -1 & 2 & 3 \\ 0 & 0 & 0 & 1 & 3 & 2 \\ 0 & 0 & 0 & 1 & 5 \end{bmatrix}$ gives rise to a homogeneous linear system. Ax = 0

i.e. $\begin{bmatrix} 1 & 4 & -1 & 2 & 3 & 0 \\ 0 & 0 & 1 & 3 & 2 & 0 \\ 0 & 0 & 0 & 1 & 5 & 0 \end{bmatrix}$ has solutions $x = sv_1 + tv_2$ (as a here)

Systems of the form Ax = 0 are called homogeneous meaning if u and v are solutions (i.e. Au = 0 and Av = 0 then A(su + tv) = 0 then so is su + tv. sAu + tAv = 0

A homogeneous system Ax=0 is always consistent, since the zero vector x=0 is a solution. Nul (A) = null space of A= { all solutions of the homogeneous section Ax=0} $\subseteq \mathbb{R}^n$

Checking answers: If we reduce A ~ A', how can we check our work? (A' could be a row exhalor form for A, or maybe a reduced row echelon form for A). A and A' have the same null vectors. eg. $A = \begin{bmatrix} 1 & 4 & -1 & 2 & 3 \\ 0 & 0 & 1 & 3 & -2 \\ 0 & 0 & 0 & 1 & 5 \end{bmatrix} \sim A' = \begin{bmatrix} 1 & 4 & 0 & 0 & -24 \\ 0 & 0 & 1 & 0 & -17 \\ 0 & 0 & 0 & 1 & 5 \end{bmatrix}$ A' has mil vectors [7], [24] Check that they are also mill vectors for A. Every null vector for B is also a null vector for AB.

If Bx = 0 then ABx = A0 = 0 $\begin{bmatrix} 0 & 1 & 2 \\ 3 & 2 & 5 \end{bmatrix} = \begin{bmatrix} 1/3 \\ 2 & 1 \end{bmatrix}$ Last week's quiz: [0][012]= 325] [23][325]= 012 [23][325]= [98] $\begin{bmatrix} 3 & 2 & 5 \\ 0 & 1 & 2 \\ 9 & 8 & 19 \end{bmatrix} \begin{bmatrix} -\frac{1}{3} \\ -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$ $\begin{bmatrix} 0 & 1 & 2 \\ 3 & 2 & 5 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} 5 & 6 \\ 12 & 18 \end{bmatrix}$ If C is an nxn matrix, the trace of C is the sum of the n entries on the main diagonal of C. (denoted to C)

If A is anxa and B is nxm, then tr(AB) = tr(BA) = trace

Fig. Solve y'' + y = x''.

A particular solution is $y = x^2 - 2$. Cleck: $y'' + y = 2 + (x^2 - 2) = x^2$.

The general solution is $y = x^2 - 2 + a \sin x + b \cos x$ where $a,b \in \mathbb{R}$ are arbitrary.

The homogenized equation y'' + y = 0 is homogeneous (so if y, and y are two solutions, then a linear Gombination ay, y + by is also a solution. The general solution of y'' + y = 0 is $y = a \sin x + b \cos x$.