

Linear Algebra

Book 3

Eg. $A = \begin{bmatrix} 1 & 3 & 0 & 4 \\ 2 & 4 & 11 & 7 \\ 0 & 3 & 0 & 4 \\ 1 & 6 & 3 & 5 \end{bmatrix}$

Expanding along the third row, $\det A = 0 \begin{vmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{vmatrix} - 3 \begin{vmatrix} 1 & 0 & 4 \\ 2 & 11 & 7 \\ 1 & 3 & 5 \end{vmatrix} + 0 \begin{vmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{vmatrix} - 4 \begin{vmatrix} 1 & 3 & 0 \\ 2 & 4 & 11 \\ 1 & 6 & 3 \end{vmatrix}$

$$= -3 \left(\begin{vmatrix} 11 & 7 \\ 3 & 5 \end{vmatrix} + 4 \begin{vmatrix} 2 & 11 \\ 1 & 3 \end{vmatrix} \right) - 4 \left(\begin{vmatrix} 1 & 3 \\ 6 & 3 \end{vmatrix} - 3 \begin{vmatrix} 2 & 11 \\ 1 & 3 \end{vmatrix} \right)$$

$$= -3(55 - 21 + 4(6 - 11)) - 4(12 - 66 - 3(6 - 11))$$

$$= 669.$$

(I checked this by computer.)

Wed. Nov. 8 Test. Come a few minutes early if you can.

No Quiz Fri. Nov. 10, 17.

I am away Fri. Nov. 17, Mon. Nov. 20. Lectures for those two days will be prerecorded - check the websites.

Recall: if $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ then $\det A = ad - bc$. A is invertible iff $\det A \neq 0$, in which case $A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$.

This formula has a generalization for $n \times n$ matrices (Cramer's Rule). This is useful although not the most computationally efficient way to compute A^{-1} if n is large.

On HW 2 you had to find A^{-1} where A is 4×4 . The entries of A^{-1} have a common denominator $\det A$.

Eg. $A = \begin{bmatrix} 1 & 2 & 5 \\ 2 & 1 & 3 \\ 7 & 6 & 4 \end{bmatrix}$, $\det A = \begin{vmatrix} 1 & 2 & 5 \\ 2 & 1 & 3 \\ 7 & 6 & 4 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 5 \\ 0 & -3 & -7 \\ 7 & 6 & 4 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & 5 \\ 0 & 3 & 7 \\ 7 & 6 & 4 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & 5 \\ 0 & 3 & 7 \\ 0 & -8 & -31 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 5 \\ 0 & 3 & 7 \\ 0 & -8 & -31 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 5 \\ 0 & 3 & 7 \\ 0 & -1 & 10 \end{vmatrix}$

$$= |1| \begin{vmatrix} 3 & 7 \\ -1 & 10 \end{vmatrix} = 1 \cdot 37.$$

A^{-1} has fractional entries with common denominator 37.
 Matrix of minors: $M = \begin{bmatrix} \begin{vmatrix} 1 & 3 \\ 2 & 4 \end{vmatrix} & \begin{vmatrix} 2 & 5 \\ 7 & 6 \end{vmatrix} & \begin{vmatrix} 1 & 2 \\ 7 & 6 \end{vmatrix} \\ \begin{vmatrix} 2 & 5 \\ 6 & 4 \end{vmatrix} & \begin{vmatrix} 1 & 5 \\ 7 & 4 \end{vmatrix} & \begin{vmatrix} 1 & 2 \\ 7 & 6 \end{vmatrix} \\ \begin{vmatrix} 2 & 5 \\ 1 & 3 \end{vmatrix} & \begin{vmatrix} 1 & 5 \\ 2 & 3 \end{vmatrix} & \begin{vmatrix} 1 & 2 \\ 2 & 1 \end{vmatrix} \end{bmatrix} = \begin{bmatrix} -14 & -13 & 5 \\ -22 & -31 & -8 \\ 1 & -7 & -3 \end{bmatrix}$

$$A^{-1} = \frac{1}{37} \begin{bmatrix} -14 & 22 & 1 \\ 13 & -31 & 7 \\ 5 & 8 & -3 \end{bmatrix} = \begin{bmatrix} -\frac{14}{37} & \frac{22}{37} & \frac{1}{37} \\ \frac{13}{37} & -\frac{31}{37} & \frac{7}{37} \\ \frac{5}{37} & \frac{8}{37} & -\frac{3}{37} \end{bmatrix}$$

← transpose;
 apply checkerboard;
 divide by det A

Check: $A A^{-1} = \frac{1}{37} \begin{bmatrix} 1 & 2 & 5 \\ 2 & 1 & 3 \\ 7 & 6 & 4 \end{bmatrix} \begin{bmatrix} -14 & 22 & 1 \\ 13 & -31 & 7 \\ 5 & 8 & -3 \end{bmatrix} = \frac{1}{37} \begin{bmatrix} 37 & 0 & 0 \\ 0 & 37 & 0 \\ 0 & 0 & 37 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \checkmark$

If A is a square matrix with integer entries and $\det A = \pm 1$, then A^{-1} also has integer entries.

Find a constant c such that the following matrix has determinant zero:

$$A = \begin{bmatrix} 5 & 3 & 6 \\ 1 & 2 & 4 \\ 7 & 7 & c \end{bmatrix} \begin{array}{l} \leftarrow u = (5 \ 3 \ 6) \\ \leftarrow v = (1 \ 2 \ 4) \\ \leftarrow w \quad u + 2v = (7 \ 7 \ 14) \end{array}$$

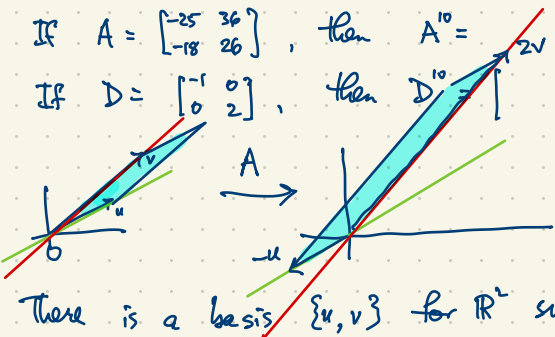
If $c = 14$ then A has linearly dependent rows so $\det A = 0$ in this case (A is not invertible).

If $c \neq 14$ then A has linearly independent rows then $w \neq (7 \ 7 \ 14)$ and $(0 \ 0 \ 1)$ is a linear combination of u, v, w i.e. Row A contains $u, v, (0 \ 0 \ 1)$.

$$\det \begin{bmatrix} 5 & 3 & 6 \\ 1 & 2 & 4 \\ 0 & 0 & 1 \end{bmatrix} = 7 \times 1 = 7 \neq 0$$

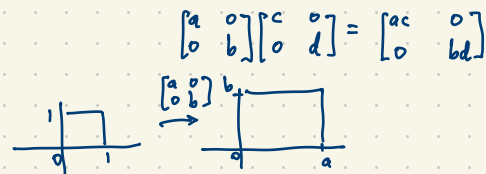
If $A = \begin{bmatrix} -25 & 36 \\ -18 & 26 \end{bmatrix}$, then $A^{10} =$

If $D = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$, then $D^{10} = \begin{bmatrix} 1 & 0 \\ 0 & 2^{10} \end{bmatrix}$



$$\det A = -2$$

$$\begin{vmatrix} -25 & 36 \\ -18 & 26 \end{vmatrix} = -25 \times 26 + 36 \times 18 = -2$$



Basis $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ standard basis
 $\begin{bmatrix} x \\ y \end{bmatrix} = xe_1 + ye_2$

There is a basis $\{u, v\}$ for \mathbb{R}^2 such that $Au = -u$, $Av = 2v$

$$\begin{aligned} A^0 u &= AAA \dots A u \\ A^2 u &= AAu = A(-u) = -Au = u \\ A^3 u &= AAA u = -u \\ &\vdots \\ A^{10} u &= u \end{aligned}$$

$$\begin{aligned} A^2 v &= AA v = A(2v) = 2Av = 4v \\ A^3 v &= 8v \\ A^{10} v &= \frac{1024}{2} v \end{aligned}$$

u, v are eigen vectors of A with corresponding eigenvalues $-1, 2$.

Definition If A is an $n \times n$ matrix, and $v \in \mathbb{R}^n$, then v is an eigenvector for A with eigenvalue λ if

$$Av = \lambda v.$$

How do we find eigenvalues and eigenvectors?

If $Av = \lambda v$ then $Av - \lambda v = 0$ i.e. $(A - \lambda I)v = 0$ i.e. $(A - \lambda I)v = 0$.

We should assume $v \neq 0$ is a nonzero null vector for $A - \lambda I$. This can only happen if $\det(A - \lambda I) = 0$.

This condition allows us to solve for the corresponding eigenvalue λ . Solve for λ ; and for each value λ (each eigenvalue), solve $(A - \lambda I)v = 0$ for the corresponding eigenvector(s) v .

$$\text{For } A = \begin{bmatrix} 25 & 36 \\ -18 & 26 \end{bmatrix}, \quad A - \lambda I = \begin{bmatrix} 25 & 36 \\ -18 & 26 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} 25-\lambda & 36 \\ -18 & 26-\lambda \end{bmatrix}.$$

$$\begin{vmatrix} 25-\lambda & 36 \\ -18 & 26-\lambda \end{vmatrix} = (25-\lambda)(26-\lambda) + 36 \cdot 18 = \lambda^2 - \lambda - 2 = (\lambda+1)(\lambda-2)$$

The characteristic polynomial has two roots $\lambda_1 = -1$, $\lambda_2 = 2$ (the two eigenvalues).

To find the corresponding eigenvectors v_1, v_2 :

First take $\lambda_1 = -1$ and solve $Av_1 = -v_1$ i.e. $(A+I)v_1 = 0$. $A+I = \begin{bmatrix} 24 & 36 \\ -18 & 27 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ (by inspection)

Or $\begin{bmatrix} 24 & 36 \\ -18 & 27 \end{bmatrix} \sim \begin{bmatrix} 1 & -\frac{3}{2} \\ -18 & 27 \end{bmatrix} \sim \begin{bmatrix} 1 & -\frac{3}{2} \\ 0 & 0 \end{bmatrix}$ has null space $\text{Span}\left\{\begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}\right\}$ with basis $\begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & -\frac{3}{2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \therefore \quad x - \frac{3}{2}y = 0$$

Introduce a parameter t .

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \frac{3}{2}t \\ t \end{bmatrix} = t \begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$$

We can take v_1 to be any nonzero scalar multiple of $\begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$. If we take $v_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$. So $Av_1 = \lambda_1 v_1 = -v_1$.

For $\lambda_2 = 2$: Solve $Av_2 = \lambda_2 v_2 = 2v_2$ i.e. $(A-2I)v_2 = 0$ where $A-2I = \begin{bmatrix} -25 & 36 \\ -18 & 26 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} -27 & 36 \\ -18 & 24 \end{bmatrix}$

A null vector of $A-2I$: $v_2 = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$ or $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ so $\begin{bmatrix} -27 & 36 \\ -18 & 24 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ i.e. $Av_2 = \lambda_2 v_2 = 2v_2$.

$v_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$ is a basis of \mathbb{R}^2 consisting of eigenvectors of A .

We started with $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ as the standard basis.

To find A^{10} : two approaches.

Let $B = [v_1 | v_2] = \begin{bmatrix} 3 & 4 \\ 2 & 3 \end{bmatrix}$. Then $AB = A \begin{bmatrix} 3 & 4 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} -3 & 8 \\ -2 & 6 \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} = BD$, $D = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$ (diagonal matrix)

so $AB^{-1} = BDB^{-1}$ i.e. $A = BDB^{-1}$.

So $A^{10} = (BDB^{-1})(BDB^{-1}) \dots (BDB^{-1}) = BD^{10}B^{-1} = \begin{bmatrix} 3 & 4 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1024 \end{bmatrix} \begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} -8183 & 12276 \\ -6138 & 9208 \end{bmatrix}$

To check: $\det(A^{10}) = (\det A)^{10} = (-2)^{10} = 1024$.

$\det \begin{bmatrix} \downarrow \\ \end{bmatrix} = 1024$

$\det A = (-25)(26) - (36)(-18) = -2$.

$\det A = (\det B)(\det D)(\det B^{-1}) = 1 \times (-2) \times 1 = -2$

Second approach: $A^{10}v_1 = v_1$, $A^{10}v_2 = 1024v_2$

$\left. \begin{aligned} v_1 &= \begin{bmatrix} 3 \\ 2 \end{bmatrix} = 3e_1 + 2e_2 \\ v_2 &= \begin{bmatrix} 4 \\ 3 \end{bmatrix} = 4e_1 + 3e_2 \end{aligned} \right\} \Rightarrow$

$\left. \begin{aligned} e_1 &= 3v_1 - 2v_2 = 3 \begin{bmatrix} 3 \\ 2 \end{bmatrix} - 2 \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ e_2 &= -4v_1 + 3v_2 = -4 \begin{bmatrix} 3 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{aligned} \right\}$

$A^{10}e_1 = A^{10}(3v_1 - 2v_2) = 3 \cdot v_1 - 2 \cdot 1024v_2 = 3 \begin{bmatrix} 3 \\ 2 \end{bmatrix} - 2048 \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \begin{bmatrix} -8183 \\ -6138 \end{bmatrix}$

$A^{10}e_2 = A^{10}(-4v_1 + 3v_2) = -4v_1 + 3 \cdot 1024v_2 = -4 \begin{bmatrix} 3 \\ 2 \end{bmatrix} + 3072 \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 12276 \\ 9208 \end{bmatrix}$

$A^{10} = \begin{bmatrix} -8183 & 12276 \\ -6138 & 9208 \end{bmatrix}$

A and D are similar: they represent the same linear transformation with respect to different choices of basis.

Ex. diagonalize the matrix $A = \begin{bmatrix} 1 & -1 & 1 \\ 2 & 1 & 2 \\ 0 & 0 & 3 \end{bmatrix}$. $\det A = \begin{vmatrix} 1 & -1 & 1 \\ 2 & 1 & 2 \\ 0 & 0 & 3 \end{vmatrix} = \begin{vmatrix} 1 & -1 \\ 2 & 1 \end{vmatrix} \cdot 3 = 6 \cdot 3 = 18$

First compute the characteristic polynomial $\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & -1 & 1 \\ 2 & 1-\lambda & 2 \\ 0 & 0 & 3-\lambda \end{vmatrix} = \begin{vmatrix} 1-\lambda & -1 \\ 2 & 1-\lambda \end{vmatrix} (3-\lambda) = [(1-\lambda)(1-\lambda) + 2] (3-\lambda)$
 $= [\lambda^2 - 5\lambda + 6] (3-\lambda) = (\lambda-2)(\lambda-3)(3-\lambda) = -(\lambda-2)(\lambda-3)^2$ has roots $2, 3, 3$ (the eigenvalues of A).

Find eigenvector v_1 for $\lambda_1 = 2$: solve $(A - \lambda_1 I)v_1 = 0$ i.e. $\begin{bmatrix} 2 & -1 & 1 \\ 2 & -1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, $v_1 = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \Rightarrow Av_1 = 2v_1$.

Find eigenvectors v_2, v_3 for $\lambda_2 = \lambda_3 = 3$: solve $(A - 3I)v = 0$ i.e. $\begin{bmatrix} 1 & -1 & 1 \\ 2 & -2 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$. Take $v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$, $v_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

Note: We want two linearly independent solutions.

Form the matrix $B = [v_1 | v_2 | v_3] = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ whose columns are the eigenvectors. (v_1, v_2, v_3 is our basis of eigenvectors)

Then $AB = BD$ where $D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$.

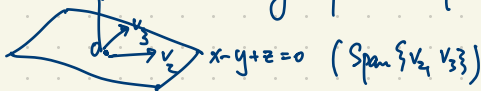
i.e. $AB B^{-1} = B D B^{-1}$

i.e. $A = B D B^{-1}$. We have diagonalized A .

$AB = A [v_1 | v_2 | v_3] = [Av_1 | Av_2 | Av_3] = [2v_1 | 3v_2 | 3v_3] = \begin{bmatrix} v_1 & v_2 & v_3 \\ \left[\begin{matrix} 2 & 3 & 3 \end{matrix} \right] \end{bmatrix} = BD$

Check: $\text{tr} A \stackrel{?}{=} \text{tr} D$, $\det A \stackrel{?}{=} \det D$
 $8 = 8$, $18 = 18$

\mathbb{R}^3 has an eigenvector v_1 with eigenvalue $\lambda_1 = 2$ and an eigenspace $\text{Span}\{v_2, v_3\}$ with eigenvalue 3 .



The eigenspace for λ is $\text{Nul}(A - \lambda I) = \{ \text{all eigenvectors having eigenvalue } \lambda \}$
 $= \{ \text{all } v \text{ satisfying } Av = \lambda v \}$.

$\begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}$ has a single eigenspace \mathbb{R}^3 with eigenvalue 5.

Actually, we don't necessarily have a basis of eigenvectors.

Consider $A = \begin{bmatrix} 7 & 16 \\ -4 & 9 \end{bmatrix}$.

Find the characteristic polynomial $\det(A - \lambda I) = \begin{vmatrix} 7-\lambda & 16 \\ -4 & 9-\lambda \end{vmatrix} = (7-\lambda)(9-\lambda) + 64 = \lambda^2 - 2\lambda + 1 = (\lambda-1)^2$
which has roots $\lambda = 1$.

Look for eigenvectors: $(A - I)v = 0$ i.e. $\begin{bmatrix} 6 & 16 \\ -4 & 8 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. Take $v_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$.