

Linear Algebra

Book 3

Eg. $A = \begin{bmatrix} 1 & 3 & 0 & 4 \\ 2 & 4 & 11 & 7 \\ 0 & 3 & 0 & 4 \\ 1 & 6 & 3 & 5 \end{bmatrix}$

Expanding along the third row, $\det A = 0 \begin{vmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{vmatrix} - 3 \begin{vmatrix} 1 & 0 & 4 \\ 2 & 11 & 7 \\ 1 & 3 & 5 \end{vmatrix} + 0 \begin{vmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{vmatrix} - 4 \begin{vmatrix} 1 & 3 & 0 \\ 2 & 4 & 11 \\ 1 & 6 & 3 \end{vmatrix}$

$$= -3 \left(\begin{vmatrix} 11 & 7 \\ 3 & 5 \end{vmatrix} + 4 \begin{vmatrix} 2 & 11 \\ 1 & 3 \end{vmatrix} \right) - 4 \left(\begin{vmatrix} 1 & 3 \\ 6 & 3 \end{vmatrix} - 3 \begin{vmatrix} 2 & 11 \\ 1 & 3 \end{vmatrix} \right)$$

$$= -3(55 - 21 + 4(6 - 11)) - 4(12 - 66 - 3(6 - 11))$$

$$= 669.$$

(I checked this by computer.)

Wed. Nov. 8 Test. Come a few minutes early if you can.

No Quiz Fri. Nov 10, 17.

I am away Fri. Nov. 17, Mon Nov 20. Lectures for those two days will be prerecorded - check the websites.

Recall: if $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ then $\det A = ad - bc$. A is invertible iff $\det A \neq 0$, in which case $A^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$.

This formula has a generalization for $n \times n$ matrices (Cramer's Rule). This is useful although not the most computationally efficient way to compute A^{-1} if n is large.

On HW 2 you had to find A^{-1} where A is 4×4 . The entries of A^{-1} have a common denominator $\det A$.

Eg. $A = \begin{bmatrix} 1 & 2 & 5 \\ 2 & 1 & 3 \\ 7 & 6 & 4 \end{bmatrix}$, $\det A = \begin{vmatrix} 1 & 2 & 5 \\ 2 & 1 & 3 \\ 7 & 6 & 4 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 5 \\ 0 & -3 & -7 \\ 7 & 6 & 4 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & 5 \\ 0 & 3 & 7 \\ 7 & 6 & 4 \end{vmatrix} = - \begin{vmatrix} 1 & 2 & 5 \\ 0 & 3 & 7 \\ 0 & -8 & -31 \end{vmatrix} = \begin{vmatrix} 1 & 2 & 5 \\ 0 & 3 & 7 \\ 0 & -1 & 10 \end{vmatrix}$

$$= |1| \begin{vmatrix} 3 & 7 \\ -1 & 10 \end{vmatrix} = 1 \cdot 37.$$

A^{-1} has fractional entries with common denominator 37.

Matrix of minors: $M = \begin{bmatrix} \begin{vmatrix} 1 & 3 \\ 2 & 4 \end{vmatrix} & \begin{vmatrix} 2 & 5 \\ 7 & 6 \end{vmatrix} & \begin{vmatrix} 2 & 1 \\ 7 & 6 \end{vmatrix} \\ \begin{vmatrix} 2 & 5 \\ 6 & 4 \end{vmatrix} & \begin{vmatrix} 1 & 5 \\ 7 & 4 \end{vmatrix} & \begin{vmatrix} 1 & 2 \\ 7 & 6 \end{vmatrix} \\ \begin{vmatrix} 2 & 5 \\ 1 & 3 \end{vmatrix} & \begin{vmatrix} 1 & 5 \\ 2 & 3 \end{vmatrix} & \begin{vmatrix} 1 & 2 \\ 2 & 1 \end{vmatrix} \end{bmatrix} = \begin{bmatrix} -14 & -13 & 5 \\ -22 & -31 & -8 \\ 1 & -7 & -3 \end{bmatrix}$

$$A^{-1} = \frac{1}{37} \begin{bmatrix} -14 & 22 & 1 \\ 13 & -31 & 7 \\ 5 & 8 & -3 \end{bmatrix} = \begin{bmatrix} -\frac{14}{37} & \frac{22}{37} & \frac{1}{37} \\ \frac{13}{37} & -\frac{31}{37} & \frac{7}{37} \\ \frac{5}{37} & \frac{8}{37} & -\frac{3}{37} \end{bmatrix}$$

← transpose;
apply checkerboard;
divide by det A

Check: $A A^{-1} = \frac{1}{37} \begin{bmatrix} 1 & 2 & 5 \\ 2 & 1 & 3 \\ 7 & 6 & 4 \end{bmatrix} \begin{bmatrix} -14 & 22 & 1 \\ 13 & -31 & 7 \\ 5 & 8 & -3 \end{bmatrix} = \frac{1}{37} \begin{bmatrix} 37 & 0 & 0 \\ 0 & 37 & 0 \\ 0 & 0 & 37 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \checkmark$

If A is a square matrix with integer entries and $\det A = \pm 1$, then A^{-1} also has integer entries.

Find a constant c such that the following matrix has determinant zero:

$$A = \begin{bmatrix} 5 & 3 & 6 \\ 1 & 2 & 4 \\ 7 & 7 & c \end{bmatrix} \begin{array}{l} \leftarrow u = (5 \ 3 \ 6) \\ \leftarrow v = (1 \ 2 \ 4) \\ \leftarrow w \quad u + 2v = (7 \ 7 \ 14) \end{array}$$

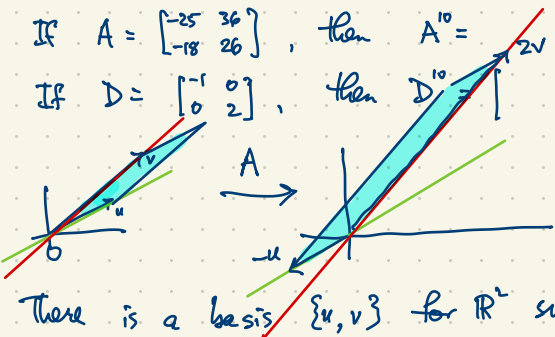
If $c = 14$ then A has linearly dependent rows so $\det A = 0$ in this case (A is not invertible).

If $c \neq 14$ then A has linearly independent rows then $w \neq (7 \ 7 \ 14)$ and $(0 \ 0 \ 1)$ is a linear combination of u, v, w i.e. Row A contains $u, v, (0 \ 0 \ 1)$.

$$\det \begin{bmatrix} 5 & 3 & 6 \\ 1 & 2 & 4 \\ 0 & 0 & 1 \end{bmatrix} = 7 \times 1 = 7 \neq 0$$

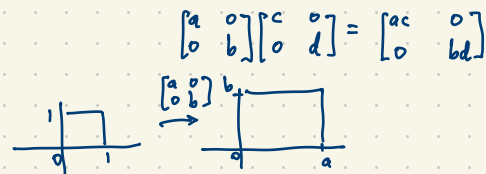
If $A = \begin{bmatrix} -25 & 36 \\ -18 & 26 \end{bmatrix}$, then $A^{10} =$

If $D = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$, then $D^{10} = \begin{bmatrix} 1 & 0 \\ 0 & 2^{10} \end{bmatrix}$



$$\det A = -2$$

$$\begin{vmatrix} -25 & 36 \\ -18 & 26 \end{vmatrix} = -25 \times 26 + 36 \times 18 = -2$$



Basis $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ standard basis
 $\begin{bmatrix} x \\ y \end{bmatrix} = xe_1 + ye_2$

There is a basis $\{u, v\}$ for \mathbb{R}^2 such that $Au = -u$, $Av = 2v$

$$\begin{aligned} A^{10}u &= AAA \dots Av \\ A^2u &= AAu = A(-u) = -Au = u \\ A^3u &= AAAu = -u \\ &\vdots \\ A^{10}u &= u \end{aligned}$$

$$\begin{aligned} A^2v &= AA v = A(2v) = 2Av = 4v \\ A^3v &= 8v \\ A^{10}v &= \frac{1024}{2}v \end{aligned}$$

u, v are eigenvectors of A with corresponding eigenvalues $-1, 2$.

Definition If A is an $n \times n$ matrix, and $v \in \mathbb{R}^n$, then v is an eigenvector for A with eigenvalue λ if

$$Av = \lambda v.$$

How do we find eigenvalues and eigenvectors?

If $Av = \lambda v$ then $Av - \lambda v = 0$ i.e. $(A - \lambda I)v = 0$ i.e. $(A - \lambda I)v = 0$.

We should assume $v \neq 0$ is a nonzero null vector for $A - \lambda I$. This can only happen if $\det(A - \lambda I) = 0$.

This condition allows us to solve for the corresponding eigenvalue λ . Solve for λ ; and for each value λ (each eigenvalue), solve $(A - \lambda I)v = 0$ for the corresponding eigenvector(s) v .

$$\text{For } A = \begin{bmatrix} 25 & 36 \\ -18 & 26 \end{bmatrix}, \quad A - \lambda I = \begin{bmatrix} 25 & 36 \\ -18 & 26 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} 25-\lambda & 36 \\ -18 & 26-\lambda \end{bmatrix}.$$

$$\begin{vmatrix} 25-\lambda & 36 \\ -18 & 26-\lambda \end{vmatrix} = (25-\lambda)(26-\lambda) + 36 \cdot 18 = \lambda^2 - \lambda - 2 = (\lambda+1)(\lambda-2)$$

The characteristic polynomial has two roots $\lambda_1 = -1$, $\lambda_2 = 2$ (the two eigenvalues).

To find the corresponding eigenvectors v_1, v_2 :

First take $\lambda_1 = -1$ and solve $Av_1 = -v_1$ i.e. $(A+I)v_1 = 0$. $A+I = \begin{bmatrix} 24 & 36 \\ -18 & 27 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$ (by inspection)

Or $\begin{bmatrix} 24 & 36 \\ -18 & 27 \end{bmatrix} \sim \begin{bmatrix} 1 & -\frac{3}{2} \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} 1 & -\frac{3}{2} \\ 0 & 0 \end{bmatrix}$ has null space $\text{Span}\left\{\begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}\right\}$ with basis $\begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$

$$\begin{bmatrix} 1 & -\frac{3}{2} \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \quad \therefore \quad x - \frac{3}{2}y = 0$$

Introduce a parameter t .

$$\begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} \frac{3}{2}t \\ t \end{bmatrix} = t \begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$$

We can take v_1 to be any nonzero scalar multiple of $\begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix}$. If we take $v_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$. So $Av_1 = \lambda_1 v_1 = -v_1$.

For $\lambda_2 = 2$: Solve $Av_2 = \lambda_2 v_2 = 2v_2$ i.e. $(A - 2I)v_2 = 0$ where $A - 2I = \begin{bmatrix} -25 & 36 \\ -18 & 26 \end{bmatrix} - \begin{bmatrix} 2 & 0 \\ 0 & 2 \end{bmatrix} = \begin{bmatrix} -27 & 36 \\ -18 & 24 \end{bmatrix}$

A null vector of $A - 2I$: $v_2 = \begin{bmatrix} 4 \\ 3 \end{bmatrix}$ or $\begin{bmatrix} 1 \\ 3 \end{bmatrix}$ so $\begin{bmatrix} -27 & 36 \\ -18 & 24 \end{bmatrix} \begin{bmatrix} 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

i.e. $Av_2 = \lambda_2 v_2 = 2v_2$.

$v_1 = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$ and $v_2 = \begin{bmatrix} 1 \\ 3 \end{bmatrix}$ is a basis of \mathbb{R}^2 consisting of eigenvectors of A .

Check: A is similar D ($A = BDB^{-1}$)

so $\text{tr} A = \text{tr} D$, $\det A = \det D$.

We started with $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, $e_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$ as the standard basis.

To find A^{10} : two approaches.

trace of $A = \text{tr} A = 1$, $\text{tr} D = 1$

Let $B = [v_1 | v_2] = \begin{bmatrix} 3 & 1 \\ 2 & 3 \end{bmatrix}$. Then $AB = A \begin{bmatrix} 3 & 1 \\ 2 & 3 \end{bmatrix} = \begin{bmatrix} -3 & 8 \\ -2 & 6 \end{bmatrix} = \begin{bmatrix} 3 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix} = BD$, $D = \begin{bmatrix} -1 & 0 \\ 0 & 2 \end{bmatrix}$ (diagonal matrix)

so $AB B^{-1} = BDB^{-1}$ i.e. $A = BDB^{-1}$.

So $A^{10} = (BDB^{-1})(BDB^{-1}) \dots (BDB^{-1}) = B D^{10} B^{-1} = \begin{bmatrix} 3 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1024 \end{bmatrix} \begin{bmatrix} 3 & -4 \\ -2 & 3 \end{bmatrix} = \begin{bmatrix} -8183 & 12276 \\ -6138 & 9208 \end{bmatrix}$

To check: $\det(A^{10}) = (\det A)^{10} = (-2)^{10} = 1024$.

$\det \begin{bmatrix} \downarrow \\ \end{bmatrix} = 1024$

$\det A = (-25)(26) - (36)(-18) = -2$.

$\det A = (\det B)(\det D)(\det B^{-1}) = 1 \times (-2) \times 1 = -2$

Second approach: $A^{10} v_1 = v_1$, $A^{10} v_2 = 1024 v_2$

$\left. \begin{aligned} v_1 &= \begin{bmatrix} 3 \\ 2 \end{bmatrix} = 3e_1 + 2e_2 \\ v_2 &= \begin{bmatrix} 1 \\ 3 \end{bmatrix} = 4e_1 + 3e_2 \end{aligned} \right\} \Rightarrow$

$\left. \begin{aligned} e_1 &= 3v_1 - 2v_2 = 3 \begin{bmatrix} 3 \\ 2 \end{bmatrix} - 2 \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \\ e_2 &= -4v_1 + 3v_2 = -4 \begin{bmatrix} 3 \\ 2 \end{bmatrix} + 3 \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \end{aligned} \right\}$

$A^{10} e_1 = A^{10} (3v_1 - 2v_2) = 3 \cdot v_1 - 2 \cdot 1024 v_2 = 3 \begin{bmatrix} 3 \\ 2 \end{bmatrix} - 2048 \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} -8183 \\ -6138 \end{bmatrix}$

$A^{10} e_2 = A^{10} (-4v_1 + 3v_2) = -4v_1 + 3 \cdot 1024 v_2 = -4 \begin{bmatrix} 3 \\ 2 \end{bmatrix} + 3072 \begin{bmatrix} 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 12276 \\ 9208 \end{bmatrix}$

$A^{10} = \begin{bmatrix} -8183 & 12276 \\ -6138 & 9208 \end{bmatrix}$

A and D are similar: they represent the same linear transformation with respect to different choices of basis.

Ex. diagonalize the matrix $A = \begin{bmatrix} 1 & -1 & 1 \\ 2 & 1 & 2 \\ 0 & 0 & 3 \end{bmatrix}$. $\det A = \begin{vmatrix} 1 & -1 & 1 \\ 2 & 1 & 2 \\ 0 & 0 & 3 \end{vmatrix} = \begin{vmatrix} 1 & -1 \\ 2 & 1 \end{vmatrix} \cdot 3 = 6 \cdot 3 = 18$

First compute the characteristic polynomial $\det(A - \lambda I) = \begin{vmatrix} 1-\lambda & -1 & 1 \\ 2 & 1-\lambda & 2 \\ 0 & 0 & 3-\lambda \end{vmatrix} = \begin{vmatrix} 1-\lambda & -1 \\ 2 & 1-\lambda \end{vmatrix} (3-\lambda) = [(1-\lambda)(1-\lambda) + 2] (3-\lambda)$
 $= [\lambda^2 - 5\lambda + 6] (3-\lambda) = (\lambda-2)(\lambda-3)(3-\lambda) = -(\lambda-2)(\lambda-3)^2$ has roots $2, 3, 3$ (the eigenvalues of A).

Find eigenvector v_1 for $\lambda_1 = 2$: solve $(A - \lambda_1 I)v_1 = 0$ i.e. $\begin{bmatrix} 2 & -1 & 1 \\ 2 & -1 & 2 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$, $v_1 = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix} \Rightarrow Av_1 = 2v_1$.

Find eigenvectors v_2, v_3 for $\lambda_2 = \lambda_3 = 3$: solve $(A - 3I)v = 0$ i.e. $\begin{bmatrix} 2 & -1 & 1 \\ 2 & -2 & 2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$. Take $v_2 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}$, $v_3 = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}$

Note: We want two linearly independent solutions.

Form the matrix $B = [v_1 | v_2 | v_3] = \begin{bmatrix} 1 & 1 & 0 \\ 2 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$ whose columns are the eigenvectors. (v_1, v_2, v_3 is our basis of eigenvectors)

Then $AB = BD$ where $D = \begin{bmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 3 & 0 \\ 0 & 0 & 3 \end{bmatrix}$.

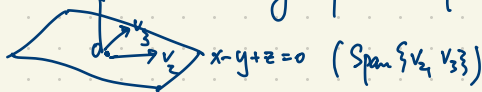
i.e. $AB B^{-1} = B D B^{-1}$

i.e. $A = B D B^{-1}$. We have diagonalized A .

$AB = A [v_1 | v_2 | v_3] = [Av_1 | Av_2 | Av_3] = [2v_1 | 3v_2 | 3v_3] = \begin{bmatrix} v_1 & v_2 & v_3 \\ \left[\begin{matrix} 2 & 3 & 3 \end{matrix} \right] \end{bmatrix} = BD$

Check: $\text{tr} A \stackrel{?}{=} \text{tr} D$, $\det A \stackrel{?}{=} \det D$
 $8 = 8$, $18 = 18$

\mathbb{R}^3 has an eigenvector v_1 with eigenvalue $\lambda_1 = 2$ and an eigenspace $\text{Span}\{v_2, v_3\}$ with eigenvalue 3 .



The eigenspace for λ is $\text{Nul}(A - \lambda I) = \{ \text{all eigenvectors having eigenvalue } \lambda \}$
 $= \{ \text{all } v \text{ satisfying } Av = \lambda v \}$.

$\begin{bmatrix} 5 & 0 & 0 \\ 0 & 5 & 0 \\ 0 & 0 & 5 \end{bmatrix}$ has a single eigenspace \mathbb{R}^3 with eigenvalue 5.

Actually, we don't necessarily have a basis of eigenvectors.

Consider $A = \begin{bmatrix} 7 & 16 \\ -4 & 9 \end{bmatrix}$.

Find the characteristic polynomial $\det(A - \lambda I) = \begin{vmatrix} 7-\lambda & 16 \\ -4 & 9-\lambda \end{vmatrix} = (7-\lambda)(9-\lambda) + 64 = \lambda^2 - 2\lambda + 1 = (\lambda-1)^2$
 which has roots 1, 1. (Only one distinct eigenvalue) $\text{Tr} A = 2$ $\det A = 1$

Look for eigenvectors: $(A - I)v = 0$ i.e. $\begin{bmatrix} 6 & 16 \\ -4 & 8 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$. Take $v_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$.

Try to complete this to a basis $v_1 = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$, $v_2 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$; $B = [v_1 | v_2] = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$

$$AB = A[v_1 | v_2] = [Av_1 | Av_2] = \begin{bmatrix} 2 & 9 \\ 1 & 5 \end{bmatrix} = B \begin{bmatrix} 1 & 4 \\ 0 & 1 \end{bmatrix} = BM$$

$AB = BM \iff A = BMB^{-1}$
 A, M are similar matrices
 having the same trace,
 determinant, characteristic poly.

$$Av_2 = \begin{bmatrix} -7 & 16 \\ -4 & 9 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = \begin{bmatrix} 9 \\ 5 \end{bmatrix}$$

$$\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 4 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 9 \\ 1 & 5 \end{bmatrix}$$

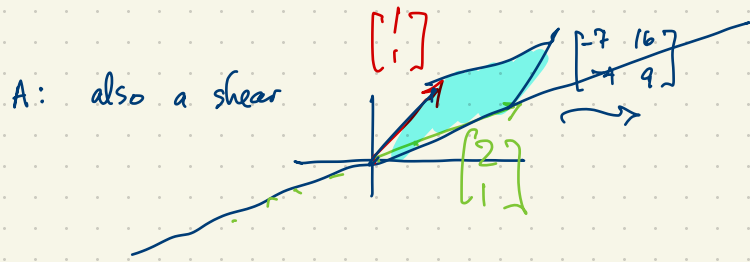
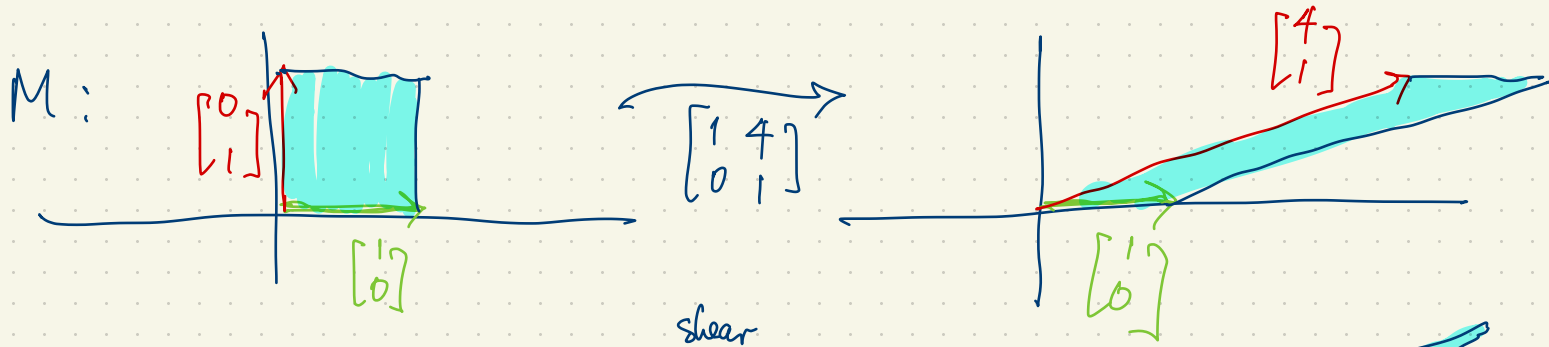
$$\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & ? \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 9 \\ 1 & 5 \end{bmatrix}$$

$$\underbrace{\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}}_B \underbrace{\begin{bmatrix} 1 & ? \\ 0 & 1 \end{bmatrix}}_M = \underbrace{\begin{bmatrix} 2 & 9 \\ 1 & 5 \end{bmatrix}}_{AB}$$

$$M = B^{-1}AB = \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 2 & 9 \\ 1 & 5 \end{bmatrix} = \begin{bmatrix} 1 & 4 \\ 0 & 1 \end{bmatrix}$$

$$B = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$$

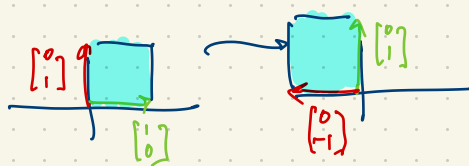
$$B^{-1} = \frac{1}{1} \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -1 & 2 \end{bmatrix}$$



A is not diagonalizable;
 \mathbb{R}^2 does not have a basis
 consisting of eigenvectors for A .
 (we have one eigenvector only).

An example with no eigenvectors or eigenvalues:

$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ represents a 90° rotation counterclockwise



Algebraically: compute the characteristic polynomial

$$\det(A - \lambda I) = \det \left(\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} - \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix} \right) = \det \begin{bmatrix} -\lambda & -1 \\ 1 & -\lambda \end{bmatrix} = \lambda^2 + 1$$

Over \mathbb{R} there are no roots of $\lambda^2 + 1$ (you cannot factor this).

Over $\mathbb{C} = \{a + bi : a, b \in \mathbb{R}\}$, however, we factor $\lambda^2 + 1 = (\lambda + i)(\lambda - i)$
so the roots $i, -i$ give two eigenvalues in \mathbb{C} . $i^2 = -1$

Find eigenvectors for A

$$Av_1 = iv_1 \iff (A - iI)v = 0 \text{ i.e. } \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}. \text{ Take } v_1 = \begin{bmatrix} i \\ 1 \end{bmatrix} \text{ as an eigenvector.}$$

$$Av_2 = -iv_2, \quad v_2 = \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

$$\text{So } A = BDB^{-1}, \quad D = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}, \quad B = \begin{bmatrix} i & -i \\ 1 & 1 \\ \underbrace{\quad} & \underbrace{\quad} \\ v_1 & v_2 \end{bmatrix}$$

$$A \begin{bmatrix} v_1 & v_2 \end{bmatrix} = \begin{bmatrix} Av_1 & Av_2 \end{bmatrix} = \begin{bmatrix} v_1 & v_2 \end{bmatrix} \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}$$

$$AB = BD$$

$$A = BDB^{-1}$$

$\{v_1, v_2\}$ is a basis of $\mathbb{C}^2 = \left\{ \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} : z_1, z_2 \in \mathbb{C} \right\}$ is a 2-dimensional vector space over

$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ is not diagonalizable over the real numbers \mathbb{R}
but it is diagonalizable over \mathbb{C} .

the field \mathbb{C} of complex numbers

Vector Spaces: Chapter 1

Scalars: real numbers / complex numbers / rational numbers / general fields

A field is a set of scalars in which we can add, subtract, multiply and divide.

A vector space is a set V whose elements are called vectors, including a zero vector $\underline{0}$, and operations $+$, $-$, scalar multiplication satisfying

1. For $\underline{u}, \underline{v} \in V$, $\underline{u} + \underline{v} \in V$. (vector + vector = vector)
2. $\underline{u} + \underline{v} = \underline{v} + \underline{u}$
3. $(\underline{u} + \underline{v}) + \underline{w} = \underline{u} + (\underline{v} + \underline{w})$ } for all $\underline{u}, \underline{v}, \underline{w} \in V$
4. $\underline{u} + \underline{0} = \underline{u} = \underline{0} + \underline{u}$
5. For each $\underline{u} \in V$, there is a vector $-\underline{u} \in V$ such that $\underline{u} + (-\underline{u}) = \underline{0}$
6. Scalar multiplication: For every scalar c and $\underline{u} \in V$, $c\underline{u} \in V$
7. Distributivity: $c(\underline{u} + \underline{v}) = c\underline{u} + c\underline{v}$
8. \dots $(c+d)\underline{u} = c\underline{u} + d\underline{u}$
9. Associativity: $(cd)\underline{u} = c(d\underline{u})$
10. $1\underline{u} = \underline{u}$

(scalar + scalar = scalar, ~~scalar + vector~~)

~~vector x vector~~

(scalar x vector = vector)

$\underset{\text{scalar}}{\uparrow} \quad \underset{\text{vector}}{\uparrow}$
 $\underline{0}\underline{u} = \underline{0}$

as follows from the axioms: $\underline{0}\underline{u} + \underline{0}\underline{u} = (0+0)\underline{u} = \underline{0}\underline{u}$. Add $-\underline{0}\underline{u}$ to both sides:

$$(\underline{0}\underline{u} + \underline{0}\underline{u}) + (-\underline{0}\underline{u}) = \underline{0}\underline{u} + (-\underline{0}\underline{u}) = \underline{0}$$

By (3), $\underline{0}\underline{u} + (\underline{0}\underline{u} + (-\underline{0}\underline{u})) = \underline{0}$

By (5) $\underline{0}\underline{u} + \underline{0} = \underline{0}$
 $\underline{0}\underline{u} = \underline{0}$

Examples of vector spaces:

\mathbb{R}^n (actually, $\mathbb{R}^{n \times 1}$ is column vectors of length n ; $\mathbb{R}^{1 \times n}$ is row vectors of length n).

Subspaces of \mathbb{R}^n

The set of all polynomials of degree $< n$ in x is an n -dimensional vector space

$$V = \{ a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1} : a_0, a_1, a_2, \dots, a_{n-1} \text{ are scalars} \}$$

$\{ 1, x, x^2, \dots, x^{n-1} \}$ is a basis for V . x is an indeterminate (i.e. not a number, just a symbol).

$\{ 1, x, x(x-1), x(x-1)(x-2), \dots, x(x-1)(x-2)\dots(x-n+1) \}$ is also a basis.

The set of all polynomials in x is a vector space which is infinite-dimensional.

A basis is $\{ 1, x, x^2, x^3, x^4, \dots \}$

Examples of polynomials: $5-3x+2x^2$, $1-x^3+3x^7+11x^8$, ...

Not polynomials: $\sin x$, $\sqrt{1+x}$, $x - \frac{x^3}{6} + \frac{x^5}{120} - \frac{x^7}{5040} + \dots$

The set of all functions $\mathbb{R} \rightarrow \mathbb{R}$.

As a subspace of this, the continuous functions $\mathbb{R} \rightarrow \mathbb{R}$.

An even smaller subspace: differentiable functions $\mathbb{R} \rightarrow \mathbb{R}$.

Even smaller: the space of "smooth functions" $V = \{ f: \mathbb{R} \rightarrow \mathbb{R} : f^{(n)} \text{ exists for all } n \geq 0 \}$

A linear transformation $T: V \rightarrow V$ is defined by $T = D^2 + I$ ($D = \frac{d}{dx}$) i.e. $Tf = f'' + f$.

The rank of T is infinite dimensional. T is not one-to-one.

A basis for $\text{Nul } T = \{ f: Tf = 0 \}$ is $\{ \sin x, \cos x \}$.

$Tf = 0$ iff $f(x) = a \sin x + b \cos x$ for some $a, b \in \mathbb{R}$.

$D: V \rightarrow V$ has $\text{Nul } D = \{ \text{constant functions} \}$ having basis $\{ 1 \}$; $\text{Nul } D$ is one-dimensional.

D has eigenvectors! eg. $D e^{3x} = 3e^{3x}$. For every $\lambda \in \mathbb{R}$, the set of eigenvectors having eigenvalue λ is one-dimensional with basis $\{ e^{\lambda x} \}$.

Fibonacci Numbers

0, 1, 1, 2, 3, 5, 8, 13, 21, 34, 55, 89, 144, ...

Recursive formula $F_n = \begin{cases} 0, & \text{if } n=0 \\ 1, & \text{if } n=1 \\ F_{n-1} + F_{n-2}, & \text{if } n \geq 2 \end{cases}$

$F_0 = 0$
 $F_1 = 1$
 $F_2 = 1$
 $F_3 = 2$
 $F_4 = 3$ etc.
 $F_5 = 8$

Consider $\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 3 \\ 2 \end{bmatrix}, \begin{bmatrix} 5 \\ 3 \end{bmatrix}, \dots$
 $v_0 \quad v_1 \quad v_2 \quad v_3 \quad v_4$

So $v_n = \begin{bmatrix} F_{n+1} \\ F_n \end{bmatrix}$ so $A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix}$ defines a map $v_n \mapsto Av_n = v_{n+1}$ i.e. $A \begin{bmatrix} F_{n+1} \\ F_n \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} F_{n+1} \\ F_n \end{bmatrix} = \begin{bmatrix} F_{n+2} \\ F_{n+1} \end{bmatrix} = v_{n+1}$.

Starting with $v_0 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$, we get $v_1 = Av_0, v_2 = Av_1 = A^2v_0, \dots, v_n = \begin{bmatrix} F_{n+1} \\ F_n \end{bmatrix} = A^n \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \text{first column of } A^n$.

$A^2 = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}, A^3 = \begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 2 & 1 \end{bmatrix}, A^4 = \begin{bmatrix} 3 & 2 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} = \begin{bmatrix} 5 & 3 \\ 3 & 2 \end{bmatrix}, \dots$

To find an explicit formula for A^n (and thereby F_n), diagonalize A .

Characteristic polynomial of A :

$\det(A - xI) = \det \left(\begin{bmatrix} 1-x & 1 \\ 1 & -x \end{bmatrix} \right) = \begin{vmatrix} 1-x & 1 \\ 1 & -x \end{vmatrix} = (1-x)(-x) - 1 = x^2 - x - 1 = (x-\alpha)(x-\beta)$ where $\alpha = \frac{1+\sqrt{5}}{2}$, $\beta = \frac{1-\sqrt{5}}{2}$
 golden ratio $\approx 1.618\dots$ $-0.618\dots$

Eigenvector for α : solution of $Av = \alpha v$ i.e. $(A - \alpha I)v = 0$

$\begin{bmatrix} 1-\alpha & 1 \\ 1 & -\alpha \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = 0$. A nonzero solution is $\begin{bmatrix} \alpha \\ 1 \end{bmatrix}$. Check: $\begin{bmatrix} 1-\alpha & 1 \\ 1 & -\alpha \end{bmatrix} \begin{bmatrix} \alpha \\ 1 \end{bmatrix} = \begin{bmatrix} (1-\alpha)\alpha + 1 \\ \alpha - \alpha \end{bmatrix} = \begin{bmatrix} 1 + \alpha - \alpha^2 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \approx 1.618\dots$

Eigenvector for β : $Av = \beta v$ i.e. $(A - \beta I)v = 0$. Take $\begin{bmatrix} \beta \\ 1 \end{bmatrix}$.

$B = \begin{bmatrix} \alpha & \beta \\ 1 & 1 \end{bmatrix}$ has the eigenvectors as its columns. $AB = \begin{bmatrix} \alpha & \beta \\ 1 & 1 \end{bmatrix} A \begin{bmatrix} \alpha \\ 1 \end{bmatrix} \begin{bmatrix} \beta \\ 1 \end{bmatrix} = \begin{bmatrix} \alpha^2 & \beta^2 \\ \alpha & \beta \end{bmatrix} = \begin{bmatrix} \alpha & \beta \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \alpha & 0 \\ 0 & \beta \end{bmatrix} = BD, D = \begin{bmatrix} \alpha & 0 \\ 0 & \beta \end{bmatrix}$.

Diagonalizing A gives $D = \begin{bmatrix} \alpha & 0 \\ 0 & \beta \end{bmatrix}$. $ABB^{-1} = BDB^{-1}$ i.e. $A = BDB^{-1}$ $D^n = \begin{bmatrix} \alpha^n & 0 \\ 0 & \beta^n \end{bmatrix} = \begin{bmatrix} \alpha^n & 0 \\ 0 & \beta^n \end{bmatrix}$

$A^n = \underbrace{(BDB^{-1})(BDB^{-1})\dots(BDB^{-1})}_{n \text{ times}} = BD^nB^{-1}$

$B = \begin{bmatrix} \alpha & \beta \\ 1 & 1 \end{bmatrix}$ $B^{-1} = \frac{1}{\sqrt{5}} \begin{bmatrix} 1 & -\beta \\ 1 & \alpha \end{bmatrix}$
 $\det B = \alpha - \beta = \sqrt{5}$

$$A^n = BDB^{-1} = \begin{bmatrix} \alpha & \beta \\ 1 & 1 \end{bmatrix} \begin{bmatrix} \alpha^n & 0 \\ 0 & \beta^n \end{bmatrix} \begin{bmatrix} 1 & -\beta \\ 1 & \alpha \end{bmatrix}$$

$$= \frac{1}{\sqrt{5}} \begin{bmatrix} \alpha^{n+1} - \beta^{n+1} & \alpha\beta^n - \beta\alpha^n \\ \alpha\beta^n - \beta\alpha^n & \alpha\beta^n - \beta\alpha^n \end{bmatrix}$$

$\alpha^n - \beta^n$
 $\alpha^{n+1} - \beta^{n+1}$
 $\alpha^n - \beta^n$

$$v_n = A^n \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \begin{bmatrix} F_{n+1} \\ F_n \end{bmatrix} = \frac{1}{\sqrt{5}} \begin{bmatrix} \alpha^{n+1} - \beta^{n+1} \\ \alpha^n - \beta^n \end{bmatrix}$$

so

$$F_n = \frac{\alpha^n - \beta^n}{\sqrt{5}} = \frac{\left(\frac{1+\sqrt{5}}{2}\right)^n - \left(\frac{1-\sqrt{5}}{2}\right)^n}{\sqrt{5}}$$

(faster than power law n^k)

$$\alpha\beta = \left(\frac{1+\sqrt{5}}{2}\right)\left(\frac{1-\sqrt{5}}{2}\right) = \frac{1-5}{4} = \frac{-4}{4} = -1$$

$$\alpha\beta = -1$$

$$\alpha + \beta = 1$$

$$\alpha - \beta = \sqrt{5}$$

eg. $F_0 = \frac{\alpha^0 - \beta^0}{\sqrt{5}} = \frac{1-1}{\sqrt{5}} = 0$

$$F_1 = \frac{\alpha^1 - \beta^1}{\sqrt{5}} = \frac{\sqrt{5}}{\sqrt{5}} = 1$$

$$F_2 = \frac{\alpha^2 - \beta^2}{\sqrt{5}} = \frac{(\alpha+1) - (\beta+1)}{\sqrt{5}} = \frac{\alpha - \beta}{\sqrt{5}} = 1$$

$$F_3 = 2 \text{ etc.}$$

$$F_{30} = \frac{\alpha^{30} - \beta^{30}}{\sqrt{5}} = 832040$$

A 2-dimensional vector space: the solutions of $y'' + y = 0$.

Over \mathbb{R} , $\{\sin x, \cos x\}$ is a basis for the solutions:

Over \mathbb{C} , $\{e^{ix}, e^{-ix}\}$ is another basis.

$$\text{If } y = e^{ix} \text{ then } y' = ie^{ix}, y'' = -e^{ix}, y'' + y = -e^{ix} + e^{ix} = 0$$

Let V be the vector space consisting of all solutions of $y'' + y = 0$.

$D: V \rightarrow V$, $Dy = y'$ is a linear transformation.

D is represented by the matrix $\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$ with respect to the first choice of basis:

$$D(a \sin x + b \cos x) = -b \sin x + a \cos x$$

$$\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -b \\ a \end{bmatrix}$$

Over \mathbb{R} , D has no (nonzero) eigenvectors.

But over \mathbb{C} , e^{ix} is an eigenvector with eigenvalue i ;
 e^{-ix} is an eigenvector with eigenvalue $-i$.

$\{e^{ix}, e^{-ix}\}$ is a basis of V consisting of eigenvectors of D .

Over \mathbb{R} : consider the vector space V consisting of all polynomials in x of degree $< n$.

$$V = \left\{ a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1} : a_0, a_1, \dots, a_{n-1} \in \mathbb{R} \right\}$$

$$D: V \rightarrow V, \quad Df(x) = f'(x) \quad \text{is linear since } D(af+bg) = (af+bg)' = af'+bg' = aDf + bDg.$$

In matrix terminology

$$D(a_0 + a_1x + a_2x^2 + \dots + a_{n-1}x^{n-1}) = a_1 + 2a_2x + 3a_3x^2 + \dots + (n-1)a_{n-1}x^{n-2}$$

$$\begin{bmatrix} 0 & 1 & 0 & 0 & \dots & 0 \\ 0 & 0 & 2 & 0 & \dots & 0 \\ 0 & 0 & 0 & 3 & \dots & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & 0 & \dots & (n-1) \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{n-1} \end{bmatrix} = \begin{bmatrix} a_1 \\ 2a_2 \\ 3a_3 \\ \vdots \\ (n-1)a_{n-1} \\ 0 \end{bmatrix}$$

Not invertible;
it has rank $n-1$

The characteristic polynomial of D is $\det[D - \lambda I] = \begin{vmatrix} -\lambda & 1 & & & \\ & -\lambda & 2 & & \\ & & -\lambda & 3 & \\ & & & \ddots & n-1 \\ & & & & -\lambda \end{vmatrix} = (-\lambda)^n$

The only root is $\lambda = 0$. An eigenvector for this eigenvalue is $\mathbf{1}$. $D\mathbf{1} = 0 = 0 \cdot \mathbf{1}$.

(Eigenvectors for eigenvalue 0 are the same thing as null vectors.)

If we move beyond polynomials then $D = \frac{d}{dx}$ has an eigenvector for every scalar λ : $D e^{\lambda x} = \lambda e^{\lambda x}$. So $e^{\lambda x}$ is an eigenvector with eigenvalue λ . This works over both \mathbb{R} and \mathbb{C} .
 ($e^{\lambda x}$ is an "eigenfunction").

Ex. Let V be the set of all rational functions in x of the form $\frac{ax+b}{x^2+8x+15}$. First decompose $\frac{ax+b}{x^2+8x+15} = \frac{ax+b}{(x+3)(x+5)} = \frac{A}{x+3} + \frac{B}{x+5}$.

We know there exist A, B (for every choice of a, b).

V is a vector space over \mathbb{R} .

$$\frac{ax+b}{x^2+8x+15} + \frac{cx+d}{x^2+8x+15} = \frac{(a+c)x + (b+d)}{x^2+8x+15} \in V$$

$$c \frac{ax+b}{x^2+8x+15} = \frac{(ca)x + cb}{x^2+8x+15} \in V$$

$\dim V = 2$ because $\frac{ax+b}{x^2+8x+15} = a \cdot \frac{x}{x^2+8x+15} + b \cdot \frac{1}{x^2+8x+15}$ expresses your vector uniquely as a linear combination of $\frac{x}{x^2+8x+15}$, $\frac{1}{x^2+8x+15}$.

We want to conclude that $\left\{ \frac{1}{x+3}, \frac{1}{x+5} \right\}$ is also a basis.
First note that $\frac{1}{x+3} = \frac{x+5}{(x+3)(x+5)} \in V$ and $\frac{1}{x+5} = \frac{x+3}{(x+3)(x+5)} \in V$.

Eg. Decompose $\frac{7x+11}{x^2+8x+5}$ into its parts by the method of partial fractions.

$$\frac{7x+11}{x^2+8x+5} = \frac{7x+11}{(x+3)(x+5)} = \frac{A}{x+3} + \frac{B}{x+5} = \frac{-5}{x+3} + \frac{12}{x+5}$$

$$7x+11 = (x+5)A + (x+3)B$$

$$\text{For } x=-3, \quad -10 = 2A \quad \text{so } A = -5.$$

$$\text{For } x=-5, \quad -24 = -2B \quad \text{so } B = 12$$

Find eigenvalues and eigenvectors of $A = \begin{bmatrix} 47 & -30 \\ 75 & -48 \end{bmatrix}$.

The characteristic polynomial is

$$\det(A - \lambda I) = \begin{vmatrix} 47-\lambda & -30 \\ 75 & -48-\lambda \end{vmatrix} = (47-\lambda)(-48-\lambda) + 2250 = \lambda^2 + \lambda - 6 = (\lambda - 2)(\lambda + 3)$$

The eigenvalues are $\lambda_1 = 2$, $\lambda_2 = -3$.

For $\lambda_1 = 2$, v_1 is a null vector of $A - 2I = \begin{bmatrix} 45 & -30 \\ 75 & -50 \end{bmatrix} \sim \begin{bmatrix} 3 & -2 \\ 3 & -2 \end{bmatrix} \sim \begin{bmatrix} 3 & -2 \\ 0 & 0 \end{bmatrix}$ so $v_1 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$

$$\text{Check: } Av_1 = \begin{bmatrix} 47 & -30 \\ 75 & -48 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 94 \\ 6 \end{bmatrix} = 2 \begin{bmatrix} 47 \\ 3 \end{bmatrix} = 2v_1 \quad \checkmark$$

For $\lambda_2 = -3$, v_2 is a null vector of $A + 3I = \begin{bmatrix} 50 & -30 \\ 75 & -45 \end{bmatrix} \sim \begin{bmatrix} 5 & -3 \\ 5 & -3 \end{bmatrix} \sim \begin{bmatrix} 5 & -3 \\ 0 & 0 \end{bmatrix}$ so $v_2 = \begin{bmatrix} 3 \\ 5 \end{bmatrix}$

$$\text{Check: } Av_2 = \begin{bmatrix} 47 & -30 \\ 75 & -48 \end{bmatrix} \begin{bmatrix} 3 \\ 5 \end{bmatrix} = \begin{bmatrix} -9 \\ -15 \end{bmatrix} = -3 \begin{bmatrix} 3 \\ 5 \end{bmatrix} \quad \checkmark$$

Another check: $\text{tr} A = -1$, $\det A = -6$.

A is similar to $\begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & -3 \end{bmatrix} = D$, $\text{tr} D = -1$, $\det D = -6$. \checkmark